

Table 1  $f(X) = - (\cdot \cdot \langle \beta, X \rangle \cdot \langle \beta, X \rangle) - (\cdot \cdot \cdot \langle \beta, X \rangle \cdot \langle \beta, X \rangle)$ 

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...,  $\beta_K$ . . . . . . . . <u>-</u>fi<sub>1</sub> . . . . . . . . . . 



 $\Sigma^- \Lambda_-$ 

 $U_{ij}=X_i(t_{ij})+\epsilon_{ij}$  , where  $\epsilon_{ij}$  , we have the second states of  $\epsilon_{ij}$  , which is the second states of  $\epsilon_{ij}$ L(T)....  $X_i$  .... Y|X X|Y

## 2 Relation to partial least squares



## 3 Implementation and numerical examples

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## References

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