



Ampoic distribution of nonparametric regression estimator for longitudinal functional data

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Abstract

The estimation of a regression functional kernel method for longitudinal functional data is considered. In the context of longitudinal data analysis, a random functional process is assumed to be observed at a small number of time points, while in the case of functional data the random realization is assumed to be observed on a dense grid. However, in all the same method can be applied to both sampling plan, a well-known number of engineering has been seen. In this paper, general results are derived for the ampouic distribution of real-valued functional data which are functional formed by a set of longitudinal functional data. A ampouic distribution for the estimator of the mean and covariance functional obtained from noisy observations in the presence of within-subject correlation is derived. The estimator is shown to be comparable to the estimator obtained from independent data, which is illustrated in a simulation study. Besides, this paper discusses the condition associated with sampling plan, which are required for the validity of local properties of kernel-based estimator for longitudinal functional data.

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1. Introduction

Modern technology and advanced computing environments have facilitated the collection and analysis of high-dimensional data, and data have repeatedly measured for a sample of subjects. The repeated measurements are often recorded over a period of time, as on an closed and bounded interval \mathcal{T} . It also could be a partial variable, such as in image or geoscience application.

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When the data are recorded on the time of an event machine, the typical functional data are obtained by the one-dimensional die. The repeated measurements all take place on a few discrete time points for each die. A significant difference between the long die in the population functional data are observed in the continuous time [2,3], the long die data are observed at a panel of discrete time points and are of event machine observations [4]. However, in practice functional data are analyzed as moving time points continuous [10], which indicates the difference between the data presented in the high-dimensional space and the moving time points continuous. The reason in his paper, kernel-based regression is obtained from observations at discrete time points continuous in the mean sense, as the observations in the continuous, are considered for the realistic reason. In the context of kernel-based nonparametric regression, the effect of sampling plan on the statistical estimation is investigated.

A similar idea has been developed in the past decade on the kernel-based regression for independent and identically distributed data, for example, see Fan and Gijbels [5]. There has been a substantial recent interest in extending the estimation of functional data on long die data [8,11,14,13,9]. The interested in the high-dimensional correlation analysis is addressed in his paper. Hall and Whitley [8] studied the Gaussian Markov process of the mean functional data repeated measurements observed on a regular grid by a moving window correlation process, and showed the influence of the high-dimensional correlation on the estimation of the malleable compared to the standard regression independent data and will disappear when the correlation functional is differentiable almost everywhere. The estimation of the functional data in fact is in the high-dimensional space and applicable for general covariance process in the functional space. This problem is also discussed by Sani and Lee [12] and Lin and Carroll [9], however, they studied the high-dimensional local properties of local polynomial estimation and in this regard ignored the high-dimensional correlation. This paper develops appropriate conditions that are required for the validity of the local properties of kernel process estimation from long die data. The conditions also provide practical guidelines for the sampling process.

The construction of his paper is the derivation of general estimation of the functional data in both one-dimensional and two-dimensional moving window functional data. The estimation of the functional data is comparable to the observations obtained from independent and identically distributed data. The results are applied to the kernel-based estimation of the mean and covariance functional, which yield a functional estimation of the estimation. In particular, of the best of our knowledge, no estimation of the functional data is available for the nonparametric estimation of covariance functional obtained from long die data continuous in the mean sense. B-spline comparison, Hall et al. [6,7] investigated a local properties of nonparametric kernel estimation of a covariance, however, the measurements are only observed from a single functional stochastic process on a random field. Although the estimation of the functional data is derived from random design in his paper, the estimation can be extended to fixed design and the sampling plan in the appropriate modification, and a functional bias and variance can also be obtained in the same manner. This is also the theoretical basis and practical guidance for the nonparametric analysis of functional data in the high-dimensional space application which are based on the estimation of the functional data. Typical examples include the construction of a functional confidence band for regression functional and confidence region

for covariance matrix, and also for the selection of bandwidth for covariance matrix estimation based on asymptotic mean squared error. Our application in the context of modeling independent data can be plotted for the modeling of longitudinal functional data using kernel-based estimation.

The remainder of the paper is organized as follows. In Section 2 we derive the general asymptotic distribution of one- and two-dimensional modeling obtained from longitudinal functional data for random design. The general asymptotic results are applied to commonly used kernel-based estimation of the mean curve and covariance matrix in Section 3. Estimation of functional density is discussed in Section 4. A simulation study is presented to evaluate the derived asymptotic results. Related data analysis in Section 5, while discussion, including potential application of the findings to asymptotic normality, are offered in Section 6.

2. General results of asymptotic distributions for random design

In this section we will define general functional data kernel-based estimation of the data for one-dimensional and two-dimensional modeling. The introduced general functional include the most commonly used type of kernel-based estimation as a special case, such as Gaussian, Nadaraya–Watson, local polynomial estimation, etc. Since Nadaraya–Watson and local polynomial estimation are motivated in practice, their asymptotic behavior in terms of bias and variance for independent data has been thoroughly studied in existing literature. However, for longitudinal functional data, particularly in regard to covariance matrix estimation, the asymptotic behavior of bias and variance of the most commonly used estimation are still largely unknown. Therefore in Section 3, the general asymptotic results developed in this section are applied to Nadaraya–Watson and local polynomial estimation in both one-dimensional and two-dimensional modeling setting. In particular, the lack of asymptotic results for the covariance matrix estimation of longitudinal functional data is an additional motivation for the definition of the two-dimensional general functional data can be applied to develop the asymptotic distribution for the estimation.

We first consider random design while estimation of the sampling plan is deferred to Section 4. In classical longitudinal design, measurements are often intended to be on a regular time grid. However, since individual measurements are often irregular, the resulting data will become sparse, the only feasible observation are obtained from subjects, with unequal number of repeated measurements per subject and different measurement times T_{ij} per individual. This sampling

variance σ^2 ,

$$Y_{ij} = X_i(T_{ij}) + \varepsilon_{ij} = \mu(T_{ij}) + \sum_{k=1}^{\infty} \zeta_{ik} \phi_k(T_{ij}) + \varepsilon_{ij}, \quad T_{ij} \in \mathcal{T}, \tag{1}$$

where $E\varepsilon_{ij} = 0$, $var(\varepsilon_{ij}) = \sigma^2$, and the number of observations, $N_i(n)$ depending on the sample size n , are considered random. We make the following assumption,

- (A1.1) The number of observations $N_i(n)$ made for the i th subject $i = 1, \dots, n$, is a random variable with $N_i(n) \stackrel{i.i.d.}{\sim} N(n)$, where $N(n) > 0$ is a positive integer-valued random variable with $\lim_{n \rightarrow \infty} p_{n \rightarrow \infty} EN(n)^2/[EN(n)]^2 < \infty$ and $\lim_{n \rightarrow \infty} p_{n \rightarrow \infty} EN(n)^4/[EN(n)EN(n)]^3 < \infty$.

In the sequel the dependence of $N_i(n)$ and $N(n)$ on the sample size is implied; i.e., $N_i = N_i(n)$ and $N(n) = N$. The observations time and measurement are assumed to be independent of the number of measurements, i.e., for any subset $J_i \subseteq \{1, \dots, N_i\}$ and for all $i = 1, \dots, n$,

- (A1.2) $(\{T_{ij} : j \in J_i\}, \{Y_{ij} : j \in J_i\})$ is independent of N_i .
 Writing $T_i = (T_{i1}, \dots, T_{iN_i})^T$ and $Y_i = (Y_{i1}, \dots, Y_{iN_i})^T$, it is easy to see that the triple $\{T_i, Y_i, N_i\}$ are i.i.d..

2.1. Asymptotic normality of one-dimensional smoother

To attain appropriate regularity conditions have been defined as a metric property, we define a new type of continuity that differs from those which are commonly used. We assume a real function $f(x, y) : \mathfrak{R}^{p+q} \rightarrow \mathfrak{R}$ is continuous on $x \in A \subseteq \mathfrak{R}^p$ uniformly in $y \in \mathfrak{R}^q$, provided that for any $x \in A$ and $\varepsilon > 0$, there exists a neighborhood of x not depending on y , containing $U(x) \subseteq \mathfrak{R}^p$, such that $|f(x', y) - f(x, y)| < \varepsilon$ for all $x' \in U(x)$ and $y \in \mathfrak{R}^q$.

For random design, (T_{ij}, Y_{ij}) are assumed to have the identical distribution (T, Y) in joint density $g(t, y)$. Assume that the observations time T_{ij} are i.i.d. with the marginal density $f(t)$, but dependence is allowed among Y_{ij} and Y_{ik} has a common observation made for the same subject. Also denote the joint density of (T_j, T_k, Y_j, Y_k) by $g_2(t_1, t_2, y_1, y_2)$, where $j \neq k$. Let v, k be given in equation (1) with $0 \leq v < k$. We assume regularity conditions for the marginal and joint densities, $f(t)$, $g(t, y)$, $g_2(t_1, t_2, y_1, y_2)$ and the mean function of the underlying process $X(t)$, i.e., $E[X(t)] = \mu(t)$, in a neighborhood of an arbitrary point $t \in \mathcal{T}$, assuming that there exists a neighborhood $U(t)$ of t such that:

- (B1.1) $\frac{d^k}{du^k} f(u)$ exists and is continuous on $u \in U(t)$, and $f(u) > 0$ for $u \in U(t)$;
 (B1.2) $g(u, y)$ is continuous on $u \in U(t)$ uniformly in $y \in \mathfrak{R}$; $\frac{d^k}{du^k} g(u, y)$ exists and is continuous on $u \in U(t)$ uniformly in $y \in \mathfrak{R}$;
 (B1.3) $g_2(u, v, y_1, y_2)$ is continuous on $(u, v) \in U(t)^2$ uniformly in $(y_1, y_2) \in \mathfrak{R}^2$;
 (B1.4) $\frac{d^k}{du^k} \mu(u)$ exists and is continuous on $u \in U(t)$.

Let $K_1(\cdot)$ be nonnegative and nonnegative kernel function in one-dimensional smoothing. The assumption for kernel $K_1 : \mathfrak{R} \rightarrow \mathfrak{R}$ are as follows. We assume a nonnegative kernel function K_1 is of order (v, k) , if

$$\int u^\ell K_1(u) du = \begin{cases} 0, & 0 \leq \ell < k, \ell \neq v, \\ (-1)^v v!, & \ell = v, \\ \neq 0, & \ell = k, \end{cases} \tag{2}$$

- (B2.1) K_1 is compact supported, $\|K_1\|^2 = \int K_1^2(u) du < \infty$;
- (B2.2) K_1 is a kernel function of order (v, ℓ) .

Let $b = b(n)$ be a sequence of bandwidths has been used in one-dimensional smoothing. We develop a multiplicative $n \rightarrow \infty$, and require

- (B3) $b \rightarrow 0, n(EN)b^{v+1} \rightarrow \infty, b(EN) \rightarrow 0$, and $n(EN)b^{2k+1} \rightarrow d^2$ for some d with $0 \leq d < \infty$.

One could see in the proof of Theorem 1 has the assumption (B3) combined with (A1.1) provide the condition which has the local properties of kernel regression estimators hold for longitudinal observational data with the presence of inhibition correlation.

Let $\{\psi_\lambda\}_{\lambda=1, \dots, l}$ be a collection of real function $\psi_\lambda : \mathfrak{R}^2 \rightarrow \mathfrak{R}$, which satisfy:

- (B4.1) $\psi_\lambda(t, y)$ are continuous on $\{t\}$ uniformly in $y \in \mathfrak{R}$;
- (B4.2) $\frac{d^k}{dt^k} \psi_\lambda(t, y)$ exist for all arguments (t, y) and are continuous on $\{t\}$ uniformly in $y \in \mathfrak{R}$.

Then we define the generalized average

$$\Psi_{\lambda n} = \frac{1}{nENb^{v+1}} \sum_{i=1}^n \sum_{j=1}^{N_i} \psi_\lambda(T_{ij}, Y_{ij}) K_1\left(\frac{t - T_{ij}}{b}\right), \quad \lambda = 1, \dots, l.$$

and

$$\mu_\lambda = \mu_\lambda(t) = \frac{d^v}{dt^v} \int \psi_\lambda(t, y) g(t, y) dy, \quad \lambda = 1, \dots, l.$$

Let

$$\sigma_{\kappa\lambda} = \sigma_{\kappa\lambda}(t) = \int \psi_\kappa(t, y) \psi_\lambda(t, y) g(t, y) dy \|K_1\|^2, \quad 1 \leq \lambda, \kappa \leq l,$$

and $H : \mathfrak{R}^l \rightarrow \mathfrak{R}$ be a function with continuous derivatives. We denote the gradient vector $(\partial H / \partial x_1)(v), \dots, (\partial H / \partial x_l)(v))^T$ by $DH(v)$ and $\bar{N} = \sum_{i=1}^n N_i/n$.

Theorem 1. *If the assumptions (A1.1), (A1.2) and (B1.1)–(B4.2) hold, then*

$$\sqrt{n\bar{N}b^{2v+1}} [H(\Psi_{1n}, \dots, \Psi_{ln}) - H(\mu_1, \dots, \mu_l)] \xrightarrow{D} \mathcal{N}(\beta, [DH(\mu_1, \dots, \mu_l)]^T \Sigma [DH(\mu_1, \dots, \mu_l)]), \tag{3}$$

where

$$\beta = \frac{(-1)^k d}{k!} \int u^k K_1(u) du \sum_{\lambda=1}^l \frac{\partial H}{\partial \mu_\lambda} \{(\mu_1, \dots, \mu_l)^T\} \frac{d^{k-v}}{dt^{k-v}} \mu_\lambda(t), \quad \Sigma = (\sigma_{\kappa\lambda})_{1 \leq \kappa, \lambda \leq l}.$$

Proof. It is seen that \bar{N} can be replaced with EN by Slutsky Theorem under (A1.1). We now have

$$\sqrt{n(EN)b^{2v+1}} [H(E\Psi_{1n}, \dots, E\Psi_{ln}) - H(\mu_1, \dots, \mu_l)] \rightarrow \beta. \tag{4}$$

Since (A1.1) and (A1.2) hold, and K_1 is of order (v, k) , using Taylor expansion of order k , one obtains

$$\begin{aligned}
 E\Psi_{\lambda n} &= \frac{1}{nb^{v+1}} E \left\{ \sum_{i=1}^n \frac{1}{EN} \sum_{j=1}^{N_i} \psi_{\lambda}(T_{ij}, Y_{ij}) K_1 \left(\frac{t - T_{ij}}{b} \right) \right\} \\
 &= \frac{1}{b^{v+1} EN} E \left\{ \sum_{j=1}^N E \left[\psi_{\lambda}(T_j, Y_j) K_1 \left(\frac{t - T_j}{b} \right) \middle| N \right] \right\} \\
 &= \frac{1}{b^{v+1}} E \left\{ \psi_{\lambda}(T, Y) K_1 \left(\frac{t - T}{b} \right) \right\} \\
 &= \mu_{\lambda} + \frac{(-1)^k}{k!} \int u^k K_1(u) du \frac{d^{k-v}}{dt^{k-v}} \mu_{\lambda}(t) b^{k-v} + o(b^{k-v}). \tag{5}
 \end{aligned}$$

Then (4) follows from a l -dimensional Taylor expansion of H of order 1 and $(\mu_1, \dots, \mu_l)^T$, combined with (5). If we can show

$$\sqrt{n(EN)b^{2v+1}} [(\Psi_{1n}, \dots, \Psi_{ln})^T - (E\Psi, \dots, E\Psi_{ln})^T] \xrightarrow{\mathcal{D}} \mathcal{N}(0, \Sigma), \tag{6}$$

in analogy to Bhattacharya and Mallik [1], and condition of DH at $(\mu_1, \dots, \mu_l)^T$ and applying similar arguments as mentioned in (5), we find $DH(E\Psi_{1n}, \dots, E\Psi_{ln}) \rightarrow DH(\mu_1, \dots, \mu_l)$. Then Cauchy–Wold decomposition yields

$$\begin{aligned}
 \sqrt{n(EN)b^{2v+1}} [H(\Psi_{1n}, \dots, \Psi_{ln}) - H(E\Psi, \dots, E\Psi_{ln})] &\xrightarrow{\mathcal{D}} \mathcal{N}(0, DH(\mu_1, \dots, \mu_l)^T \\
 &\quad \Sigma DH(\mu_1, \dots, \mu_l)), \tag{7}
 \end{aligned}$$

combined with (4), leading to (3).

It remains to show (6). Observe that (A1.1) and (A1.2), one has

$$\begin{aligned}
 &n(EN)b^{2v+1} \text{cov}(\Psi_{\lambda n}, \Psi_{\kappa n}) \\
 &= \frac{1}{b} E \left\{ \frac{1}{EN} \left[\sum_{j=1}^N \psi_{\lambda}(T_j, Y_j) K_1 \left(\frac{t - T_j}{b} \right) \right] \left[\sum_{k=1}^N \psi_{\kappa}(T_k, Y_k) K_1 \left(\frac{t - T_k}{b} \right) \right] \right\} \\
 &\quad - \frac{EN}{b} E \left[\frac{1}{EN} \sum_{j=1}^N \psi_{\lambda}(T_j, Y_j) K_1 \left(\frac{t - T_j}{b} \right) \right] \\
 &\quad \times E \left[\frac{1}{EN} \sum_{k=1}^N \psi_{\kappa}(T_k, Y_k) K_1 \left(\frac{t - T_k}{b} \right) \right] \\
 &\equiv I_1 - I_2.
 \end{aligned}$$

It follows that $I_2 = O(b) = o(1)$ from the definition of (5). For I_1 , it can be written as

$$\begin{aligned}
 I_1 &= \frac{1}{b} E \left[\frac{1}{EN} \sum_{j=1}^N \psi_\lambda(T_j, Y_j) \psi_\kappa(T_j, Y_j) K_1^2 \left(\frac{t - T_j}{b} \right) \right] \\
 &\quad + \frac{1}{b} E \left[\frac{1}{EN} \sum_{1 \leq j \neq k \leq N} \psi_\lambda(T_j, Y_j) \psi_\kappa(T_k, Y_k) K_1 \left(\frac{t - T_j}{b} \right) K_1 \left(\frac{t - Y_k}{b} \right) \right] \\
 &\equiv Q_1 + Q_2.
 \end{aligned}$$

Applying (A1.1) and (A1.2), one has

$$\begin{aligned}
 Q_1 &= \frac{1}{b} E \left\{ \frac{1}{EN} \sum_{j=1}^N E \left[\psi_\lambda(T_j, Y_j) \psi_\kappa(T_j, Y_j) K_1^2 \left(\frac{t - T_j}{b} \right) \middle| N \right] \right\} \\
 &= \frac{1}{b} E \left[\psi_\lambda(T, Y) \psi_\kappa(T, Y) K_1^2 \left(\frac{t - Y}{b} \right) \right] = \sigma_{\lambda\kappa} + o(1).
 \end{aligned}$$

Then (4) will hold, observing (A1.1) and the following arguments have given the local properties of the kernel-based estimator in the presence of bivariate correlation in longitudinal data,

$$\begin{aligned}
 Q_2 &= \frac{1}{bEN} E \left\{ \sum_{1 \leq j \neq k \leq N} E \left[\psi_\lambda(T_j, Y_j) \psi_\kappa(T_k, Y_k) K_1 \left(\frac{t - T_j}{b} \right) K_1 \left(\frac{t - T_k}{b} \right) \middle| N \right] \right\} \\
 &= \frac{EN(N-1)}{bEN} E \left[\psi_\lambda(T_1, Y_1) \psi_\kappa(T_2, Y_2) K_1 \left(\frac{t - T_1}{b} \right) K_1 \left(\frac{t - T_2}{b} \right) \right] \\
 &= \frac{bEN(N-1)}{EN} \int_{\mathbb{R}^4} \psi_\lambda(t - ub, y_1) \psi_\kappa(t - vb, y_2) K_1(u) K_2(v) \\
 &\quad \times g_2(t - ub, t - vb, y_1, y_2) du dv dy_1 dy_2 \\
 &= \frac{bEN(N-1)}{EN} \int_{\mathbb{R}^2} \psi_\lambda(t, y_1) \psi_\kappa(t, y_2) g_2(t, t, y_1, y_2) dy_1 dy_2 + o(b) = o(1),
 \end{aligned}$$

i.e., the bivariate correlation can be ignored while deriving the asymptotic variance. \square

2.2. Asymptotic normality of two-dimensional smoother

The general asymptotic result can be extended to two-dimensional smoothing. Let (\mathbf{v}, \mathbf{k}) denote the multi-indices $\mathbf{v} = (v_1, v_2)$ and $\mathbf{k} = (k_1, k_2)$, hence $|\mathbf{v}| = v_1 + v_2$ and $|\mathbf{k}| = k_1 + k_2$. In two-dimensional smoothing, more regularity assumptions are needed for joint density. Let $f_2(s, t)$ be the joint density of (T_j, T_k) , and $g_4(s, t, s', t', y_1, y_2, y'_1, y'_2)$ the joint density of $(T_j, T_k, T_{j'}, T_{k'}, Y_j, Y_k, Y_{j'}, Y_{k'})$ where $j \neq k, (j, k) \neq (j', k')$. Denote the covariance function $C(s, t) = \text{cov}(X(T_j), X(T_k) | T_j = s, T_k = t)$. The following regularity conditions are assumed, where $U(s, t)$ is some neighborhood of $\{(s, t)\}$,

(C1.1) $\frac{d^{|\mathbf{k}|}}{du^{k_1} dv^{k_2}} f_2(u, v)$ exists and is continuous on $(u, v) \in U(s, t)$, and $f_2(u, v) > 0$ for $(u, v) \in U(s, t)$;

(C1.2) $g_2(u, v, y_1, y_2)$ is continuous on $(u, v) \in U(s, t)$ uniformly in $(y_1, y_2) \in \mathfrak{R}^2$; $\frac{d^{|k|}}{du^{k_1} dv^{k_2}} g_2(u, v, y_1, y_2)$ is continuous on $(u, v) \in U(s, t)$ uniformly in $(y_1, y_2) \in \mathfrak{R}^2$;

(C1.3) $g_4(u, v, u', v', y_1, y_2, y'_1, y'_2)$ is continuous on $(u, v, u', v') \in U(s, t)^2$ uniformly in $(y_1, y_2, y'_1, y'_2) \in \mathfrak{R}^4$;

(C1.4) $\frac{d^{|k|}}{du^{k_1} dv^{k_2}} C(u, v)$ is continuous on $(u, v) \in U(s, t)$.

Let K_2 be a nonnegative bivariate kernel function defined in the n -dimensional smoothing. The empirical kernel K_2 is a follo

(C2.1) K_2 is compact supported with $\|K_2\|^2 = \int_{\mathfrak{R}^2} K_2^2(u, v) du dv < \infty$, and is symmetric in the two coordinates u and v .

(C2.2) K_2 is a kernel function of order $(|v|, |k|)$, i.e.,

$$\sum_{\ell_1 + \ell_2 = |l|} \int_{\mathfrak{R}^2} u^{\ell_1} v^{\ell_2} K_2(u, v) du dv = \begin{cases} 0, & 0 \leq |l| < |k|, |l| \neq |v|, \\ (-1)^{|v||v|!}, & |l| = |v|, \\ \neq 0, & |l| = |k|. \end{cases} \quad (8)$$

Let $h = h(n)$ be a sequence of bandwidths defined in n -dimensional smoothing, while it is possible that the bandwidths defined for two samples may be different. Since the ill focus on the estimation of the covariance function has a symmetric about the diagonal, it is efficient to consider the identical bandwidth for the two samples. The asymptotic is developed as $n \rightarrow \infty$ as follo

(C3) $h \rightarrow 0, nEN^2h^{|v|+2} \rightarrow \infty, hEN^3 \rightarrow 0$, and $nE[N(N-1)]h^{2|k|+2} \rightarrow e^2$ for some $0 \leq e < \infty$.

Similar to the one-dimensional smoothing case, a empirical (C3) and (A1.1) generate the local properties of the bivariate kernel-based estimator in the presence of bivariate correlation.

Let $\{\phi_\lambda\}_{\lambda=1, \dots, l}$ be a collection of real functions $\phi_\lambda : \mathfrak{R}^4 \rightarrow \mathfrak{R}, \lambda = 1, \dots, l$, satisfying

(C4.1) $\phi_\lambda(s, t, y_1, y_2)$ are continuous on $\{(s, t)\}$ uniformly in $(y_1, y_2) \in \mathfrak{R}^2$;

(C4.2) $\frac{d^{|k|}}{ds^{k_1} dt^{k_2}} \phi_\lambda(s, t, y_1, y_2)$ is finite for all samples (s, t, y_1, y_2) and are continuous on $\{(s, t)\}$ uniformly in $(y_1, y_2) \in \mathfrak{R}^2$.

Then the general eighth order of n -dimensional smoothing are defined by, for $1 \leq \lambda \leq l$,

$$\Phi_{\lambda n} = \Phi_{\lambda n}(s, t) = \frac{1}{nE[N(N-1)]h^{|v|+2}} \sum_{i=1}^n \sum_{1 \leq j \neq k \leq N_i} \phi_\lambda(T_{ij}, T_{ik}, Y_{ij}, Y_{ik}) \times K_2\left(\frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h}\right).$$

Let

$$m_\lambda = m_\lambda(s, t) = \sum_{v_1 + v_2 = |v|} \frac{d^{|v|}}{ds^{v_1} dt^{v_2}} \int_{\mathfrak{R}^2} \phi_\lambda(s, t, y_1, y_2) g_2(s, t, y_1, y_2) dy_1 dy_2, \quad 1 \leq \lambda \leq l,$$

and

$$\omega_{\kappa\lambda} = \omega_{\kappa\lambda}(s, t) = \int_{\mathfrak{M}^2} \phi_{\kappa}(s, t, y_1, y_2) \phi_{\lambda}(s, t, y_1, y_2) g_2(s, t, y_1, y_2) dy_1 dy_2 \|K_2\|^2,$$

$$1 \leq \kappa, \lambda \leq l,$$

and $H : \mathfrak{M}^l \rightarrow \mathfrak{R}$ is a function which can be further defined as a prior defined.

Theorem 2. *If assumptions (A1.1), (A1.2) and (C1.1)–(C4.2) hold, then*

$$\begin{aligned} & \sqrt{n\bar{N}(\bar{N} - 1)h^{2|v|+2}} [H(\Phi_{1n}, \dots, \Phi_{ln}) - H(m_1, \dots, m_l)] \\ & \xrightarrow{D} \mathcal{N}(\gamma, [DH(m_1, \dots, m_l)]^T \Omega [DH(m_1, \dots, m_l)]), \end{aligned} \tag{9}$$

where

$$\begin{aligned} \gamma &= \frac{(-1)^{|k|} e}{|k|!} \sum_{\lambda=1}^l \left\{ \sum_{k_1+k_2=|k|} \int_{\mathfrak{M}^2} u^{k_1} v^{k_2} K_2(u, v) du dv \frac{d^{|k|}}{ds^{k_1} dt^{k_2}} \right. \\ & \quad \left. \times \int_{\mathfrak{M}^2} \phi_{\lambda}(s, t, y_1, y_2) g_2(s, t, y_1, y_2) dy_1 dy_2 \right\} \\ & \quad \times \left\{ \frac{\partial H}{\partial m_{\lambda}}(m_1, \dots, m_l)^T \right\}, \end{aligned}$$

$$\Omega = (\omega_{\kappa\lambda})_{1 \leq \kappa \leq l}.$$

The proof of Theorem 2 essentially follows that of Theorem 1 with appropriate modification which are required for functional modeling.

3. Applications to nonparametric regression estimators for functional or longitudinal data

Although the estimation of kernel-based estimators has been introduced in literature, Nadaraya-Watson and local polynomial, especially local linear estimator, are the most commonly used nonparametric modeling techniques in longitudinal functional data analysis. Deo and Bhattacharya, in their study on the asymptotic behavior of bias and variance of the estimator for non-functional longitudinal data, have been able to provide a formal proof of the asymptotic behavior of the estimator for functional data. In particular, asymptotic behavior of the estimator for functional data is studied. Therefore, in this section, we apply the asymptotic behavior of the general functional Nadaraya-Watson and local linear estimator of regression function and covariance surface of bivariate functional data.

3.1. Asymptotic distributions of mean estimators

We apply Theorem 1 on the local asymptotic behavior of the commonly used Nadaraya-Watson kernel estimator $\hat{\mu}_N(t)$ and local linear estimator $\hat{\mu}_L(t)$ for functional/longitudinal

da a:

$$\hat{\mu}_N(t) = \left[\sum_{i=1}^n \sum_{j=1}^{N_i} K_1 \left(\frac{t - T_{ij}}{b} \right) Y_{ij} \right] / \left[\sum_{i=1}^n \sum_{j=1}^{N_i} K_1 \left(\frac{t - T_{ij}}{b} \right) \right], \tag{10}$$

$$\hat{\mu}_L(t) = \hat{\alpha}_0(t) = \arg \min_{(\alpha_0, \alpha_1)} \left\{ \sum_{i=1}^n \sum_{j=1}^{N_i} K_1 \left(\frac{t - T_{ij}}{b} \right) [Y_{ij} - (\alpha_0 + \alpha_1(T_{ij} - t))]^2 \right\}. \tag{11}$$

Corollary 1. *If assumptions (A1.1), (A1.2), and (B1.1)–(B3) hold with $v = 0$ and $k = 2$, then*

$$\sqrt{n\bar{N}b}[\hat{\mu}_N(t) - \mu(t)] \xrightarrow{\mathcal{D}} \mathcal{N} \left(\frac{d \mu^{(2)}(t) f(t) + 2\mu^{(1)}(t) f^{(1)}(t)}{f(t)} \sigma_{K_1}^2, \frac{\text{var}(Y|T=t) \|K_1\|^2}{f(t)} \right), \tag{12}$$

where d is as in (B3), $\sigma_{K_1}^2 = \int u^2 K_1(u) du$

Here $w_{ij} = K_1((t - T_{ij})/b)/(nb)$, where K_1 is a kernel function of order $(0, 2)$, satisfying (B2.1) and (B2.2), and $\hat{\alpha}_1(t)$ is an estimator of the function $\mu'(t)$ of μ at t .

Obeying the Corollary 1 implies $\hat{\mu}_N(t) \xrightarrow{P} \mu(t)$, let $\hat{f}(t) = \sum_i \sum_j w_{ij}/N_i$, in each case $\hat{f}(t) \xrightarrow{P} f(t)$ in analogy of Corollary 1. We proceed to show $\hat{\alpha}_1(t) \xrightarrow{P} \mu'(t)$. Denote $\sigma_{K_1}^2 = \int u^2 K_1(u) du$, the kernel function $\tilde{K}_1(t) = -tK_1(t)/\sigma_{K_1}^2$, and define $\Psi_{\lambda n}$, $1 \leq \lambda \leq 3$ by $\psi_1(u, y) = y, \psi_2(u, y) \equiv 1, \psi_3(u, y) = u - t$. Obeying the \tilde{K}_1 is of order $(1, 3)$, $\hat{f}(t) \xrightarrow{P} f(t)$, and define

$$\tilde{H}(x_1, x_2, x_3) = \frac{x_1 - x_2 \hat{\mu}_N(t)}{x_3 - bx_2^2/\hat{f}(t) \cdot \sigma_{K_1}^2} \quad \text{and} \quad H(x_1, x_2, x_3) = \frac{x_1 - x_2 \mu(t)}{x_3}.$$

Then

$$\begin{aligned} \hat{\alpha}_1(t) &= \tilde{H}(\Psi_{1n}, \Psi_{2n}, \Psi_{3n}) \\ &= \left[H(\Psi_{1n}, \Psi_{2n}, \Psi_{3n}) + \frac{\Psi_{2n}(\mu(t) - \hat{\mu}_N(t))}{\Psi_{3n}} \right] \frac{\Psi_{3n}}{\Psi_{3n} + b^2 \Psi_{2n}^2/\hat{f}(t) \cdot \sigma_{K_1}^2}. \end{aligned}$$

Note that $\mu_1 = (\mu'f + mf')(t), \mu_2 = f'(t)$, and $\mu_3 = f(t)$, implying $\Psi_{\lambda n} - \mu_\lambda = O_p(1/\sqrt{n\bar{N}b^3})$, for $\lambda = 1, 2, 3$, by Theorem 1. Using Slutsky's Theorem, $|\tilde{H}(\Psi_{1n}, \Psi_{2n}, \Psi_{3n}) - \mu'(t)| = O_p(1/\sqrt{n\bar{N}b^3})$ follows.

For the asymptotic distribution of $\hat{\mu}_L$, note that

$$\hat{\mu}_L(t) = \frac{\sum_i \frac{1}{EN} \sum_j w_{ij} Y_{ij} - \sum_i \frac{1}{EN} \sum_j w_{ij} (T_{ij} - t) \hat{\alpha}_1(t)}{\sum_i \frac{1}{EN} \sum_j w_{ij}}.$$

Considering $\sqrt{n\bar{N}b} \sum_i \frac{1}{EN} \sum_j w_{ij} (T_{ij} - t) = \sqrt{n\bar{N}b} \sigma_{K_1}^2 b^2 \Psi_{2n}$. Since \tilde{K}_1 is of order $(1, 3)$, Theorem 1 implies $\Psi_{2n} = f'(t) + O_p(1/\sqrt{n\bar{N}b^3})$, which yields $\sqrt{n\bar{N}b} \sigma_{K_1}^2 b^2 \Psi_{2n} = \sqrt{n\bar{N}b^5} \sigma_{K_1}^2 f'(t) + \sigma_{K_1}^2 O_p(b) = o_p(1)$ by obeying $n\bar{N}b^5 \rightarrow d^2$ for $0 \leq d < \infty$. Since $\hat{f}(t) \xrightarrow{P} f(t)$ and $|\hat{\alpha}_1(t) - \mu'(t)| = O_p(1/\sqrt{n\bar{N}b^3}) = o_p(1)$, we find

$$\begin{aligned} \lim_{n \rightarrow \infty} \sqrt{n\bar{N}b} [\hat{\mu}_L(t) - \mu(t)] &\stackrel{D}{=} \lim_{n \rightarrow \infty} \sqrt{n\bar{N}b} \\ &\times \left\{ \frac{\sum_i \frac{1}{EN} \sum_j w_{ij} Y_{ij} - \mu'(t) \sum_i \frac{1}{EN} \sum_j w_{ij} T_{ij} + t \mu'(t) \sum_i \frac{1}{EN} \sum_j w_{ij}}{\sum_i \frac{1}{EN} \sum_j w_{ij}} - \mu(t) \right\}. \end{aligned}$$

Using the kernel K_1 of order $(0, 2)$, we define $\Psi_{\lambda n}$, $1 \leq \lambda \leq 3$, though $\psi_1(u, y) = y, \psi_2(u, y) = u$ and $\psi_3(u, y) \equiv 1$, using $v = 0, k = 2, l = 3$ and $H(x_1, x_2, x_3) = [x_1 - \mu'(t)x_2 + t\mu'(t)x_3]/x_3$. Then (13) follows by applying Theorem 1. \square

3.2. Asymptotic distributions of covariance estimators

Note that in model (1), $cov(Y_{ij}, Y_{ik}|T_{ij}, T_{ik}) = cov(X(T_{ij}), X(T_{ik})) + \sigma^2 \delta_{jk}$, where δ_{jl} is 1 if $j = k$ and 0 otherwise. Let $C_{ijk} = (Y_{ij} - \hat{\mu}(T_{ij}))(Y_{ik} - \hat{\mu}(T_{ik}))$ be the covariance, where $\hat{\mu}(t)$ is the estimated mean function obtained from the previous step. In advance, $\hat{\mu}(t) = \hat{\mu}_N(t)$ or $\hat{\mu}(t) = \hat{\mu}_L(t)$. In each case we have $E[C_{ijk}|T_{ij}, T_{ik}] \approx cov(X(T_{ij}), X(T_{ik})) + \sigma^2 \delta_{jk}$. Therefore,

the diagonal of the covariance should be removed, i.e., only $C_{ijk}, j \neq k$, should be included in the data for the covariance surface modeling step, as proposed in Santoli and Lee [12] and Yao et al. [15].

Commonly used nonparametric regression estimators of the covariance surface, $C(s, t) = E\{[X(T_1) - \mu(T_1)][X(T_2) - \mu(T_2)] | T_1 = s, T_2 = t\}$, are the two-dimensional Nadaraya-Watson estimator and local linear estimator defined as follows:

$$\hat{C}_N(s, t) = \frac{\left[\sum_{i=1}^n \sum_{j \neq k} K_2\left(\frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h}\right) C_{ijk} \right]}{\left[\sum_{i=1}^n \sum_{j \neq k} K_2\left(\frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h}\right) \right]}, \tag{16}$$

$$\hat{C}_L(s, t) = \hat{\beta}_0(s, t) = \arg \min_{\beta} \left\{ \sum_{i=1}^n \sum_{j \neq k} K_2\left(\frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h}\right) \times [C_{ijk} - f(\beta, (s, t), (T_{ij}, T_{ik}))] \right\}$$

$\phi_1(t_1, t_2, y_1, y_2) = (y_1 - \mu(t_1))(y_2 - \mu(t_2))$, $\phi_2(t_1, t_2, y_1, y_2) = y_1 - \mu(t_1)$, and $\phi_3(t_1, t_2, y_1, y_2) \equiv 1$, then $\prod_{t,s \in \mathcal{T}} |\Phi_{pm}| = O_p(1)$, for $p = 1, 2, 3$, by Lemma 1 of Yao et al. [16]. This implies that $\prod_{t,s \in \mathcal{T}} |\Phi_{2n}| O_p(1/(\sqrt{nb})) = O_p(1/(\sqrt{nb}))$ and $\prod_{t,s \in \mathcal{T}} |\Phi_{3n}| O_p(1/(\sqrt{nb})) = O_p(1/(\sqrt{nb}))$. Since $\prod_{t \in \mathcal{T}} |\hat{\mu}(t) - \mu(t)|^2 = O_p(1/(nb))$ and negligible compared to Φ_{1n} , then $\tilde{C}_N(s, t)$, of $C(s, t)$ obtained from C_{ijk} in a multiplicative equation also obtained from \tilde{C}_{ijk} , denoted by $\tilde{C}_N(t, s)$.

Therefore, the efficiency of the multiplicative decomposition of $\tilde{C}_N(s, t)$ follows (18). Choose $v = (0, 0)$, $|k| = 2$, $\phi_1(s, t, y_1, y_2) = (y_1 - \mu(s))(y_2 - \mu(t))$, $\phi_2(s, t, y_1, y_2) \equiv 1$ and $H(x_1, x_2) = x_1/x_2$ in Theorem 2, then $\tilde{C}_N(s, t) = H(\Psi_{1n}, \Psi_{2n})$. To compute $\gamma_N(s, t)$, we have $DH(m_1, m_2) = (1/m_2, -m_1/m_2^2)$, and note $m_1(s, t) = \int_{\mathbb{R}^2} (y_1 - \mu(s))(y_2 - \mu(t)) g_2(s, t, y_1, y_2) dy_1 dy_2 = f_2(s, t)C(s, t)$ and $m_2(s, t) = f_2(s, t)$. One has $(d^2/dt^2)m_1(s, t) = [(d^2 f_2/dt^2)C + 2(df_2/dt)(dC/dt) + f_2(d^2 C/dt^2)](s, t)$, $(d^2/dt^2)m_2(s, t) = d^2 f_2(s, t)/dt^2$ and similarly, since the special case leading to the bias term in (12). For the multiplicative variance, note that $\omega_{11} = \|K_2\|^2 \int_{\mathbb{R}^2} (y_1 - \mu(s))^2 (y_2 - \mu(t))^2 g_2(s, t, y_1, y_2) dy_1 dy_2 = E[(Y_1 - \mu(T_1))^2 (Y_2 - \mu(T_2))^2 | T_1 = s, T_2 = t] f_2(s, t) \|K_2\|^2$, $\omega_{12} = \omega_{21} = \|K_2\|^2 f_2(s, t) C(s, t)$, $\omega_{22} = \|K_2\|^2 f_2(s, t)$, and $DH(m_1, m_2) = (1/m_2, -m_1/m_2^2)$, yielding the variance term in (12). \square

Corollary 4. *If the assumptions (A1.1), (A1.2), and (C1.1) (C3) hold with $|v| = 0$ and $|k| = 2$, then*

$$\sqrt{n\tilde{N}(\tilde{N} - 1)h^2} [\hat{C}_L(s, t) - C(s, t)] \xrightarrow{D} \mathcal{N} \left(\frac{e}{4} \sigma_{K_2}^2 [d^2 C(s, t)/ds^2 + d^2 C(s, t)/dt^2], \frac{v(s, t) \|K_2\|^2}{f_2(s, t)} \right), \tag{19}$$

where e is as in (C3), $v(s, t) = \text{var}\{(Y_1 - \mu(T_1))(Y_2 - \mu(T_2)) | T_1 = s, T_2 = t\}$, $\sigma_{K_2}^2 = \int_{\mathbb{R}^2} (u^2 + v^2) K_2(u, v) du dv$, $\|K_2\|^2 = \int_{\mathcal{R}^2} K_2^2(u, v) du dv$.

Proof. In analogy to the proof of Corollary 3, the local linear estimator $\hat{C}_L(s, t)$ obtained from C_{ijk} in a multiplicative equation also obtained from \tilde{C}_{ijk} , denoted by $\tilde{C}_L(t, s)$. All denote the solution of (17), after substituting \tilde{C}_{ijk} for C_{ijk} , by $\tilde{\beta}(s, t) = (\tilde{\beta}_0(s, t), \tilde{\beta}_1(s, t), \tilde{\beta}_2(s, t))$, and in fact $\tilde{\beta}_0(s, t) = \tilde{C}_L(s, t)$. For simplicity, let $W_{ijk} = K_2((s - T_{ij})/h, (t - T_{ik})/h)/(nh^2)$ and $\sum_{i,j \neq k}$ "i abbreviation of $\sum_{i=1}^n \sum_{j \neq k}$ ". Algebraic calculation yields that

$$\tilde{C}_L = \frac{\sum_{i,j \neq k} \tilde{C}_{ijk} W_{ijk} - \tilde{\beta}_1 \sum_{i,j \neq k} W_{ijk} T_{ij} + \tilde{\beta}_1 \sum_{i,j \neq k} W_{ijk} s - \tilde{\beta}_2 \sum_{i,j \neq k} W_{ijk} T_{ik} + \tilde{\beta}_2 \sum_{i,j \neq k} W_{ijk} t}{\sum_{i,j \neq k} W_{ijk}}$$

$$\tilde{\beta}_1 = \frac{R_{00}(S_{10}S_{02} - S_{01}S_{11}) + R_{10}(S_{00}S_{02} - S_{01}S_{20}) - R_{01}(S_{00}S_{11} - S_{10}S_{02})}{S_{00}S_{20}S_{02} - S_{00}S_{11}^2 - S_{10}^2S_{02} + S_{10}S_{01}S_{11} + S_{20}S_{10}S_{11} - S_{01}S_{20}^2},$$

$$\tilde{\beta}_2 = \frac{R_{00}(S_{10}S_{11} - S_{01}S_{02}) - R_{10}(S_{00}S_{11} - S_{01}S_{20}) + R_{01}(S_{00}S_{20} - S_{10}^2)}{S_{00}S_{20}S_{02} - S_{00}S_{11}^2 - S_{10}^2S_{02} + S_{10}S_{01}S_{11} + S_{20}S_{10}S_{11} - S_{01}S_{20}^2},$$

hence

$$R_{pq} = \sum_{i,j \neq k} W_{ijk} (T_{ij} - s)^p (T_{ik} - t)^q \tilde{C}_{ijk}, \quad S_{pq} = \sum_{i,j \neq k} W_{ijk} (T_{ij} - s)^p (T_{ik} - t)^q.$$

Note that $\tilde{\beta}_1$ and $\tilde{\beta}_2$ are local linear estimators of the partial derivatives of $C(s, t)$, $dC(s, t)/ds$ and $dC(s, t)/dt$, respectively. In analogy to the proof of Corollary 2, it can be shown that $|\tilde{\beta}_1(s, t) - dC(s, t)/ds| = O_p(1/\sqrt{nEN(N-1)h^4})$ and $|\tilde{\beta}_2(s, t) - dC(s, t)/dt| = O_p(1/\sqrt{n\bar{N}(\bar{N}-1)h^4})$ by applying Theorem 2. Then one can substitute $dC(s, t)/ds$, $dC(s, t)/dt$ for $\tilde{\beta}_1(s, t)$, $\tilde{\beta}_2(s, t)$ in $\tilde{C}_L(s, t)$, and denote the resulting estimator $C_L^*(s, t)$. It is easy to see that

$$\lim_{n \rightarrow \infty} \sqrt{n\bar{N}(\bar{N}-1)h^2} [C_L(s, t) - C(s, t)] \stackrel{\mathcal{D}}{=} \lim_{n \rightarrow \infty} \sqrt{n\bar{N}(\bar{N}-1)h^2} [C_L^*(s, t) - C(s, t)].$$

We define $\Phi_{\lambda n}$, $1 \leq \lambda \leq 4$, through $\phi_1(s, t, y_1, y_2) = (y_1 - \mu(s))(y_2 - \mu(t))$, $\phi_2(s, t, y_1, y_2) = \dots$

where in Corollary 3 and 4, $f(t)$ is replaced by $1/|T|$ and $f(s, t)$ is replaced by $1/|T|^2$, where $|T|$ is the length of the interval.

5. Simulation study

An medical diagnostic procedure is designed to compare two populations. The key finding in his paper is that the empirical functional longitudinal are comparable to those obtained from independent data, i.e., the influence of within-subject covariance does not play a significant role in determining the empirical bias and variance. For simplicity, we focus on the local polynomial mean estimator which are of the Nadaraya-Watson estimator.

We first generated $M = 200$ samples consisting of $n = 50$ i.i.d. random observations each. Following model (1), the simulated process has a mean function $\mu(t) = (t - 1/2)^2$, $0 \leq t \leq 1$ which has a constant second derivative $\mu^{(2)}(t) = 2$, and a constant within-subject covariance function derived from a random intercept $\xi_1 \stackrel{i.i.d.}{\sim} N(0, \lambda_1)$, where $\lambda_1 = 0.01$ and $\phi_1(t) = 1$, $0 \leq t \leq 1$. The mean term in (1) are $\varepsilon_{ij} \stackrel{i.i.d.}{\sim} N(0, \sigma^2)$, where $\sigma^2 = 0.01$. A random design is used, where the number of observations for each subject N_i are chosen from $\{2, 3, 4, 5\}$ with equal likelihood and the location of the observations are normally distributed on $[0, 1]$, i.e., $T_{ij} \stackrel{i.i.d.}{\sim} U[0, 1]$. For comparison, we generated $M = 200$ samples of $n = 50$ i.i.d. random observations which have the same structure as in model (1) but without subject correlation. Letting $\xi_{i1} = 0$ and $\varepsilon_{ij} \stackrel{i.i.d.}{\sim} N(0, \sqrt{\lambda_1 + \sigma^2})$ lead to independent data with the same mean and variance function. Therefore, the order of data has the same empirical distribution for the local polynomial mean estimator. We also generated $M = 200$ correlated and independent samples, respectively, consisting of $n = 200$ observations each to demonstrate the asymptotic behavior with the increasing sample size n .

Here we use the Epanechnikov kernel function, i.e., $K_1(u) = 3/4(1 - u^2)\mathbf{1}_{[-1,1]}(u)$, where $\mathbf{1}_A(u) = 1$ if $u \in A$ and 0 otherwise for any set A . Note that $n(EN)b^{2k+1} \rightarrow d^2$ in (B3), $\mu^{(2)}(t) = 2$, $var(Y|T = t) = \lambda_1 + \sigma^2 = 0.02$, and the design density $f(t) = 1$, where $k = 2$ for local polynomial estimator and b is the bandwidth of the mean estimator. From the above construction, one can calculate the empirical bias and variance of the local polynomial mean estimator $\hat{\mu}_L(t)$ using Corollary 2 which is in fact applicable for both correlated and independent data. Since the bias and variance are both constant in the limit function form, for convenience we compare the empirical integrated squared bias and variance with the empirical integrated squared bias and variance obtained using Monte Carlo average from $M = 200$ simulated samples based on $\int_0^1 E\{[\hat{\mu}_L(t) - \mu(t)]^2\} dt = \int_0^1 \{E[\hat{\mu}_L(t)] - \mu(t)\}^2 dt + \int_0^1 \{E[\hat{\mu}_L(t)] - \mu(t)\}^2 dt$. The empirical integrated squared bias and variance are given by

$$AIBIAS = \frac{1}{2} \sigma_{K_1}^2 b^4, \quad AIVAR = \frac{0.02 \times \|K_1\|^2}{n \bar{N} b}, \tag{20}$$

and the empirical integrated mean squared error $AIMSE = AIBIAS + AIVAR$, where $\sigma_{K_1}^2 = \int u^2 K_1(u) du$, $\|K_1\|^2 = \int K_1^2(u) du$ and $\bar{N} = (1/n) \sum_{i=1}^n N_i$, while the empirical integrated squared bias, variance and mean squared error are denoted by EIBIAS, EIVAR and EIMSE,

The empirical and empirical integrated squared bias, variance and mean squared error are shown in Fig. 1 for the correlated/independent data with sample size $n = 50/n = 200$, respectively. From Fig. 1, it is obvious that the empirical approximation improved by increasing the sample size. The empirical integrated squared bias, variance and AIMSE agree with the

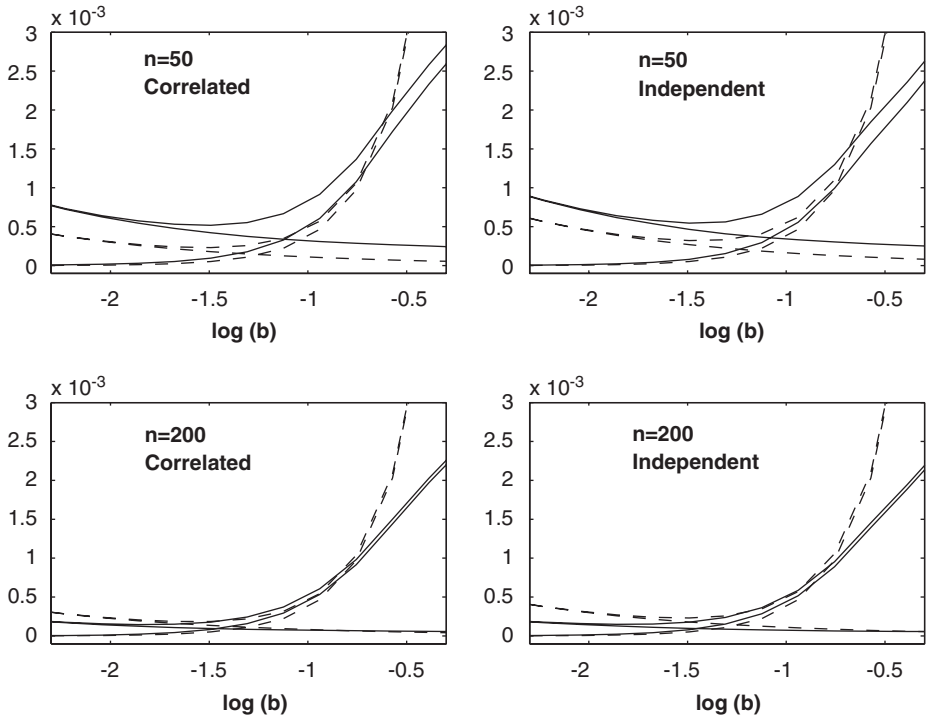


Fig. 1. Shows the empirical bias (solid, including EIBIAS, EIVAR, EIMSE) and asymptotic bias (dashed, including AIBIAS, AIVAR, AIMSE) versus $\log(b)$ for correlated (left panel) and independent (right panel) data with different sample size $n = 50$ (top panel) and $n = 200$ (bottom panel), where b is the bandwidth in the smoothing. In each panel, the increased bias is the one which increases in $\log(b)$, the increased variance is the one which decreases in $\log(b)$, and the curves each other while the increased mean squared error which is large than both in increased bias and variance for a bandwidth b , all decrease first and then increase after reaching a minimum.

empirical bias (EIBIAS, EIVAR and EIMSE) for both correlated and independent data. For the same sample size n , the asymptotic approximation for correlated and independent data are well comparable in pattern and magnitude. This provides the evidence that the different correlation indeed does not have obvious influence on the asymptotic behavior of the local polynomial estimator compared to the standard one obtained from independent data, which is consistent with theoretical derivation.

6. Discussion

In this paper, the asymptotic derivation of kernel-based nonparametric regression estimator for functional longitudinal data are studied. In particular, the

defined in (A1.1) and (A1.2), fitted equally spaced defined in (A1*), and some calling been them. The proposed likelihood are ended of more complicated case, which panel data here observation for different between obtained a set of common time point using a longitudinal follow-up. If considering random defined, the density of the j th observation time T_j could be assumed to be $f_j(t)$, then the likelihood are readily applied on his case in his appropriate modification in his respect of the different marginal density.

The general approach of dimension reduction in nonlinear and bilinear modeling are applied on the kernel-based estimation of the mean and covariance function, which yield a principal component dimension of the estimation. To the best of our knowledge, there are no approach of dimension reduction available in literature for nonparametric estimation of covariance function obtained from observed nonlinear longitudinal functional data. This procedure theoretical basis and practical guidance for the nonparametric analysis of functional longitudinal data in his important potential application has been based on the approach of dimension reduction. For example, a principal confidence band construction for the regression curve of the covariance surface can be constructed based on the approach of dimension reduction. Since, due to the heavy computational load, commonly used procedure (such as cross-validation) for bandwidth selection in multidimensional engineering are not feasible, one important research problem is to seek efficient approaches for choosing the modeling parameters. All of functional principal component analysis, an increasing population tool for functional data analysis, is based on eigen-decomposition of the estimated covariance function. Thus, the influence of the approach of covariance estimation on the estimated eigenfunction is another important research of interest.

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