

### Outline

- Review of community detection
- Community extraction
- Simulation study
- Real data analysis
- Asymptotic consistency
- Future work

### Network data

#### Data: links between nodes

- Social and friendship networks, citation networks
- Marketing, recommender systems
- Computer, mobile, sensor networks
- World Wide Web
- Gene regulatory networks, food webs

#### **Notation**

#### Given a network N = (V, E)

- V is the set of nodes, E is the set of edges.
- N is represented by its adjacency matrix A:

$$A_{ij} = \begin{cases} 1 & \text{if there is an edge from node } i \text{ to node } j, \\ 0 & \text{otherwise.} \end{cases}$$

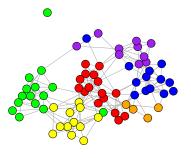
 A can be symmetric (undirected network) or asymmetric (directed network).

# Community detection

- Communities: many links within and few links between
- Community detection is typically formulated as finding a partition  $V = V_1 \cup \cdots \cup V_K$  which gives "tight" communities in some suitable sense.
- For simplicity, give criteria for partitioning into two communities  $V_1$  and  $V_2$ .

# Example: a school friendship network

Colors represent grades



# Graph cuts

Min-cut: minimize

$$R = \sum_{i \in V_1, j \in V_2} A_{ij} \ .$$

Trivial solution of  $V_1 = V$  or  $V_2 = V$ .

# Graph cuts

Min-cut: minimize

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Trivial solution of  $V_1 = V$  or  $V_2 = V$ .

• Ratio cut (Wei and Cheng, 1989): minimize

$$\frac{R}{|V_1|\cdot|V_2|},$$

where  $|V_1|$  and  $|V_2|$  are the sizes of the two communities.

# Graph cuts

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• Ratio cut (Wei and Cheng, 1989): minimize

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Normalized cut (Shi and Malik, 2000): minimize

$$\frac{R}{D_1} + \frac{R}{D_2}$$

where  $D_k = \sum_{i \in V_k, j \in V} A_{ij}$  is the total number of edges from nodes in  $V_k$ .

# Modularity (Newman050Nev

$$Q = \sum_{k} \left[ \frac{O_{kk}}{L} - \left( \frac{D_{k}}{L} \right)^{2} \right]$$

- Q is the sum of observed expected under the configuration model: probability of edge between nodes with degrees d<sub>i</sub>, d<sub>i</sub> is d<sub>i</sub>d<sub>i</sub>/L.
- Typically solved by an eigenvalue method via relaxing max<sub>s<sub>i</sub>=±1</sub> s<sup>T</sup>Ms to max<sub>||s||=1</sub> s<sup>T</sup>Ms.

# Limitation of partition methods

- Many real-world networks contain nodes with few links that may not belong to any community ("background").
- The "strength" of a community depends on links between nodes not related to the community.
- Determining the number of communities is difficult.

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# Community extraction

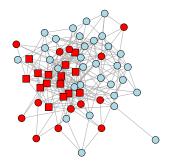
- Allow for background nodes that only have sparse links to other nodes.
- Extract communities sequentially: at each step look for a set with a large number of links within and a small number of links to the rest of the network.
- Stop when no more meaningful communities exist.

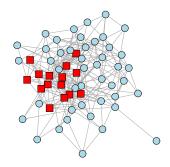
# Toy example

- One community with 15 nodes, total 60 nodes.
- Links between community members form independently with probability 0.5.
- Links between community members and other nodes form independently with probability 0.1.
- Links between other nodes form independently with probability 0.1.
- Compare partition into two communities (via modularity) to extraction of a single community.

Shapes represent the truth, colors represent results.

Partition Extraction





#### Extraction criterion

#### Maximize

$$W(S) = \frac{O(S)}{|S|^2} - \frac{B(S)}{|S| \cdot |S^c|}$$

where

$$O(S) = \sum_{i,j \in S} A_{ij} \ , \ B(S) = \sum_{i \in S,j \in S^c} A_{ij} \ .$$

The links within the complement of set *S* do not matter.

# Adjusted criterion

- In sparse networks, tends to pick small disconnected components first.
- To avoid small communities, can use

#### Maximize

$$W_a(S) = |S| \cdot |S^c| \left( \frac{O(S)}{|S|^2} - \frac{B(S)}{|S| \cdot |S^c|} \right).$$

The factor  $|S| \cdot |S^c|$  encourages more balanced solutions.

# **Algorithm**

- Tabu Search (Glover, 1986; Glover and Laguna, 1997): a local optimization technique based on label switching.
- Switch labels to improve the value of the criterion but each node has to keep its label for at least T iterations.
- Run the algorithm for many randomly ordered nodes.

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#### Numerical evaluation

- S is the extracted community.
- $C_S$  is the true community that matches S best.

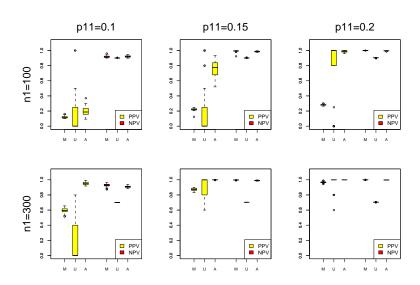
#### PPV and NPV

$$PPV = \frac{|C_S \cap S|}{|S|}$$
 Purity 
$$NPV = 1 - \frac{|C_S \cap S^c|}{|S^c|}$$
 Completeness

### Simulation I

- One community with background
- n = 1000
- $n_1 = 100,200,300$
- $p_{12} = 0.05, p_{22} = 0.05$
- $p_{11} = 0.1, 0.15, 0.2$

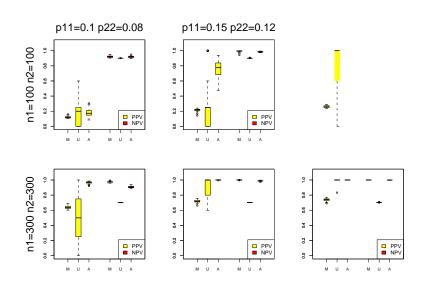
# Results of simulation I



### Simulation II

- Two communities plus background
- n = 1000
- $n_1 = 100,300, n_2 = 100,300$
- $p_{12} = p_{23} = p_{13} = p_{33} = 0.05$
- $p_{11} = 0.1, 0.15, 0.2$
- $p_{22} = 0.08, 0.12, 0.16$

# Results for simulation II



### Outline

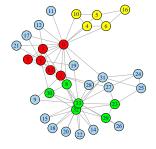
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- √ Community extraction
- √ Simulation study
- Real data analysis

### Karate club network

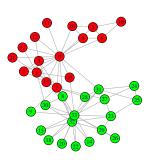
- Friendships between 34 members of a karate club (Zachary, 1977).
- This club has subsequently split into two parts following a disagreement between an instructor (node 0) and an administrator (node 33).

# Karate club network

#### Community extraction



# Modularity



### Political books network

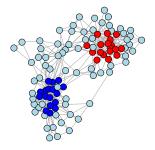
Links in the political books network (Newman, 2006) represent pairs of books frequently bought together on amazon.com.

Blue: liberal

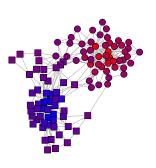
Red: conservative

# Political books network

Community extraction



Modularity

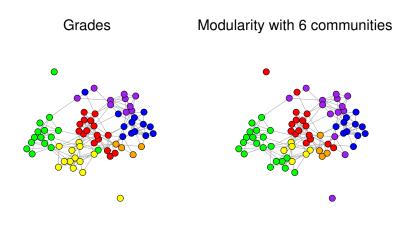


# School friendship network

The school friendship network is complied from the National Longitudinal Study of Adolescent Health (AddHealth).

Grade 7: red Grade 8: blue Grade 9: green Grade 10: yellow Grade 11: purple Grade 12: orange

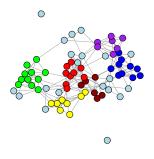
# School friendship network

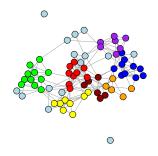


# School friendship network

Extracting 6 communities

Extracting 7 communities





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### **Block models**

One of the simplest random graph models for communities

- Each node is assigned to a block independently of other nodes, with probability  $_k$  for block k,  $\sum_{k=1}^{K}$   $_k = 1$ .
- Given that node i belongs to block a and node j belongs to block b,  $P[A_{ij} = 1] = p_{ab}$ , and all edges are independent.
- Parametrized as  $P_n = {}_nP$ , where  ${}_n = P_n[A_{ii} = 1] \rightarrow 0$ .
- Expected node degree n = n n
- Can stipulate background: assume p<sub>aK</sub> < p<sub>bb</sub> for all a = 1,..., K, and all b = 1,..., K − 1.

# Asymptotic consistency result

- For simplicity, assume one community and background  $(K = 2 \text{ with parameters } p_{11}, p_{12}, p_{22}, )$ .
- Let c be the true labels,  $\hat{c}^{(n)}$  the estimated labels.

#### Theorem

For any 0 < < 1, if  $p_{11} > p_{12}$ ,  $p_{11} > p_{22}$  and  $p_{11} + p_{22} > 2p_{12}$ ,  $\frac{n}{\log n} \to \infty$ , the maximizer  $\hat{\boldsymbol{c}}^{(n)}$  of both unadjusted and adjusted criteria satisfies

$$P[\hat{\boldsymbol{c}}^{(n)} = \boldsymbol{c}] \rightarrow 1$$
 as  $n \rightarrow \infty$ .

- Holds for  $p_{12} = p_{22} = p < p_{11}$
- Proof: apply Bickel and Chen (PNAS, 2009)

# Bickel & Chen consistency framework

- Assume a block model with known K
- Given a proposed label assignment s, true labels c, let R be the confusion matrix with

$$R_{ab}(\mathbf{s},\mathbf{c}) = \frac{1}{n} \sum_{i=1}^{n} I(s_i = a, c_i = b)$$
.

- Many criteria, including ours, can be written as a function of the confusion matrix.
- Key condition: the population version of the criterion is maximized by the "correct" confusion matrix diag(1,..., k).

#### Future work

- Eigenvalue method
- Determining the number of communities
- Adjusted criterion

$$W_a(S) = \left(|S| \cdot |S^c|\right) \quad \left(\frac{O(S)}{|S|^2} - \frac{B(S)}{|S| \cdot |S^c|}\right)$$